

UNIT-VI

3-PHASE TRANSFORMERS

3- ϕ transformers

$$v = V_m \sin \omega t ; i = I_m \sin(\omega t - \phi)$$

$$P_{(1-\phi)} = v \cdot i$$

$$= V_m \sin \omega t \cdot I_m \sin(\omega t - \phi)$$

$$= \frac{V_m I_m}{2} \cdot 2 \sin \omega t \cdot \sin(\omega t - \phi)$$

$$= -\frac{V_m}{\sqrt{2}} \cdot \frac{I_m}{\sqrt{2}} [\cos(\omega t - \omega t + \phi) - \cos(\omega t + \omega t - \phi)]$$

$$= V \cdot I [\cos \phi - \cos(2\omega t - \phi)]$$

$$P_{(2-\phi)} = V \cdot I \cos \phi - V \cdot I \cos(2\omega t - \phi)$$

$$P = \frac{dW}{dt} \quad \omega = \frac{d\theta}{dt}$$

$$= v \frac{dq}{dt}$$

$$= v \cdot i$$

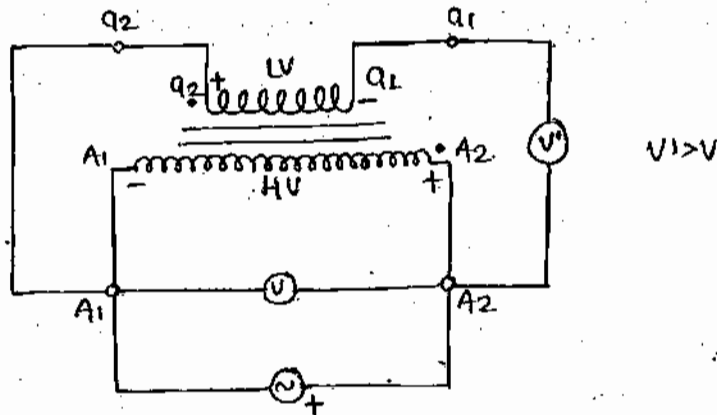
So, a 1- ϕ power suffers from double freq. component.

3000 kVA

option 1: 1x 3000 kVA, 3- ϕ unit

option 2: 3x 1000 kVA, 1- ϕ TF connected in 3- ϕ bank

POLARITY TEST



figs- additive polarity

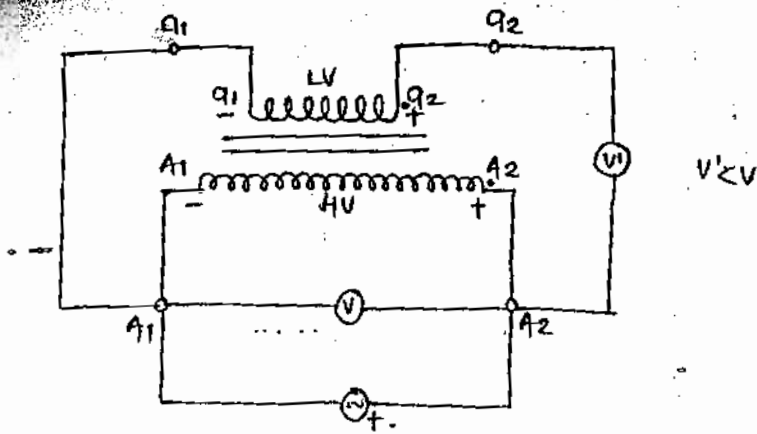


Fig:- Subtractive polarity.

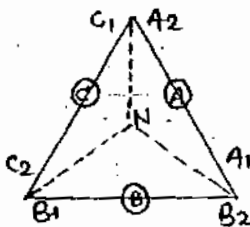
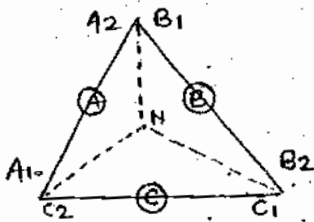
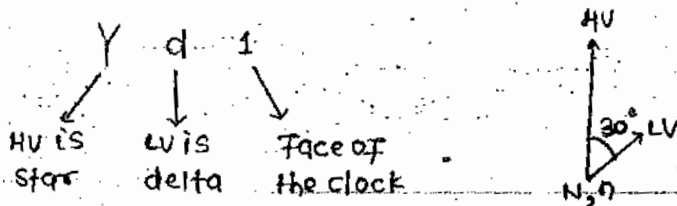
* Phasor Groups →

Group (1) :- $0^\circ \rightarrow Yy0, Dd0, Dz0$

Group (2) :- $180^\circ \rightarrow Yy6, Dd6, Dz6$

Group (3) :- $30^\circ (\text{lag}) \rightarrow Yd1, Dy1, Yz1$

Group (4) :- $30^\circ (\text{lead}) \rightarrow Yd11, Dy11, Yz11$

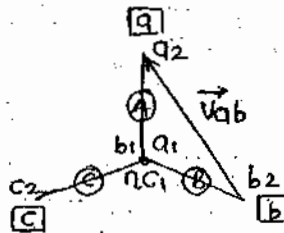
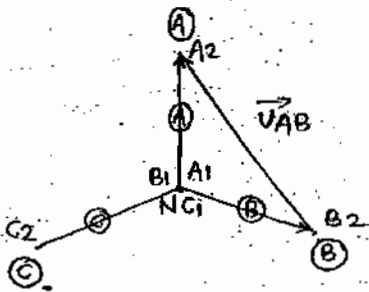
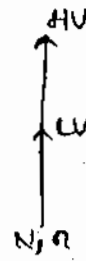
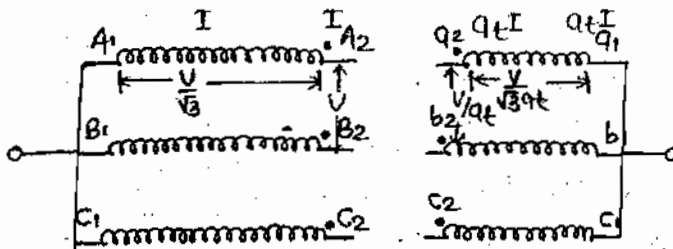


* British Practise for phasor groups →

- (1) Phasor seq. in ABC.
- (2) HV line (A-N) phasor always at 0 o'clock.
- (3) HV line 'A' terminal to be taken from A_2
- (4) $\vec{V}_{q_2 a_1}$ is in phase with $\vec{V}_{A_2 A_1}$.

Y40 →

$$q_t = \frac{NHV}{NLV}$$



$$V_{AB} = V_{AN} - V_{BN}$$

$$V_{AN} = V_{AB} + V_{BN}$$

Phase vol. transformation Ratio = $\frac{V}{\sqrt{3}} : \frac{V}{\sqrt{3}q_t} = q_t : 1$

line vol. transformation Ratio = $V : \frac{V}{q_t} = q_t : 1$

$$SHV = \sqrt{3}VI$$

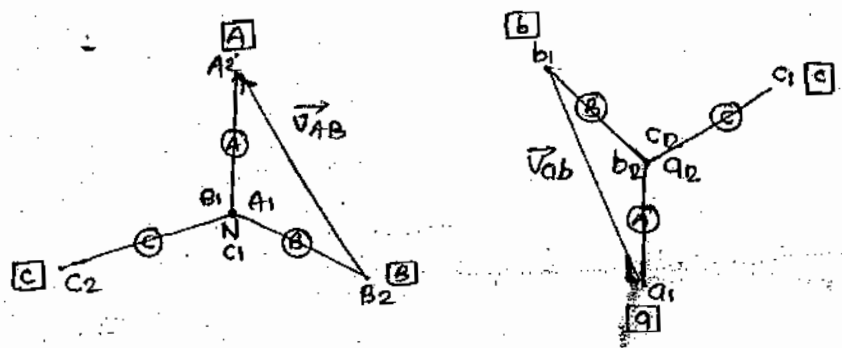
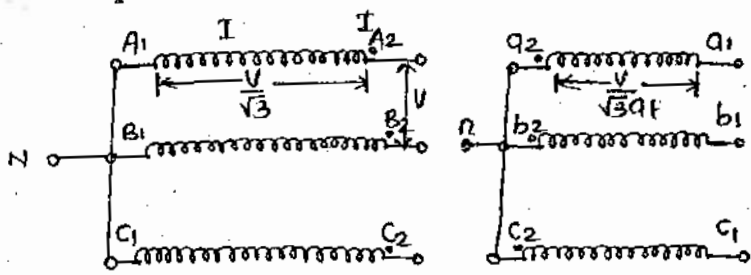
$$SLV = \sqrt{3} \left(\frac{V}{q_t} \right) (q_t I)$$

$$= \sqrt{3}VI$$

$$= SHV$$

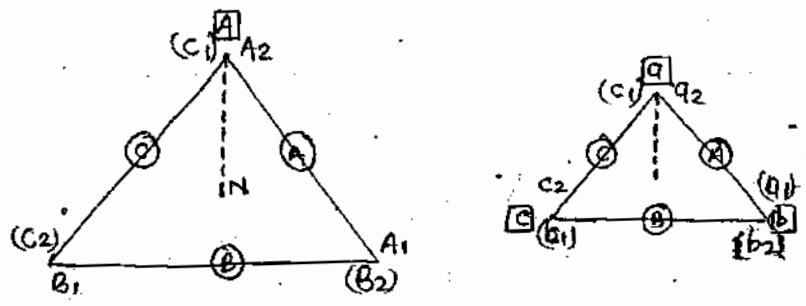
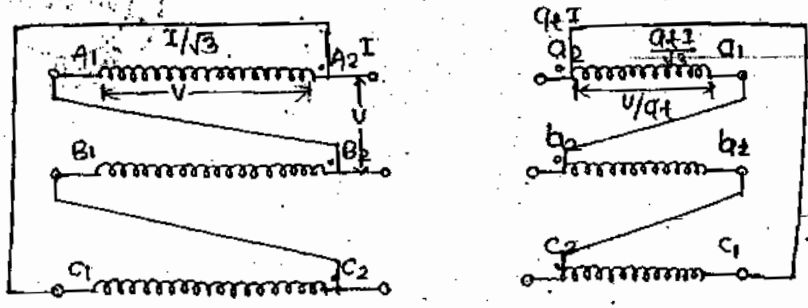
$$\boxed{SLV = SHV}$$

Y96 →



Dd0 →

* The British convention for Δ - Δ connection is that the HV side Δ & LV side Δ with the same combinations; this shows that $a_1, b_2, b_1, c_2, c_1, a_2$



phase vol. X mation ratio = $V:V = a+1$

line vol. X mation ratio = $V:\frac{V}{a+1} = a+1$

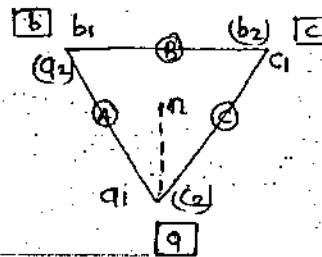
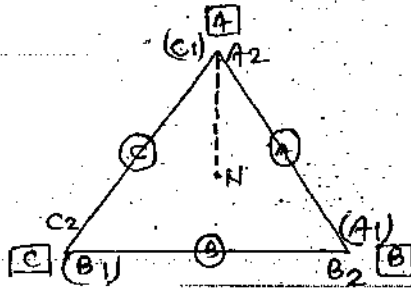
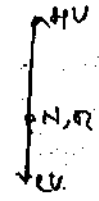
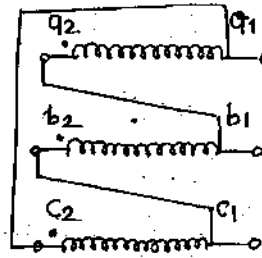
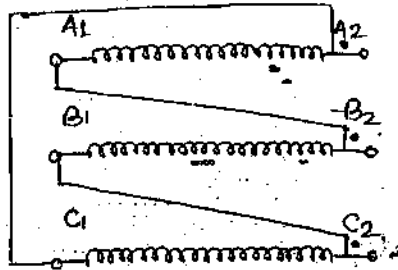
$S_{HV} = \sqrt{3}VI$

$S_W = \sqrt{3}\left(\frac{V}{a+1}\right)(a+1)$

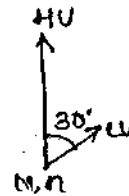
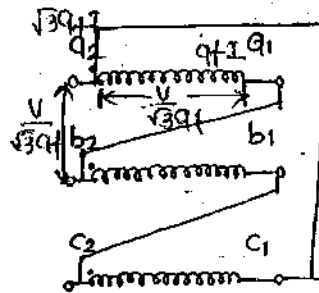
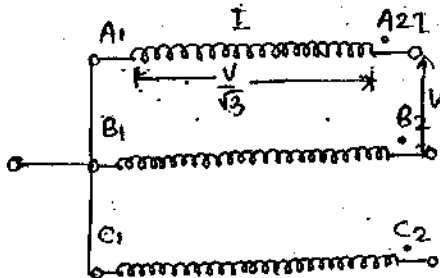
$= \sqrt{3}VI$

$S_W = S_{HV}$

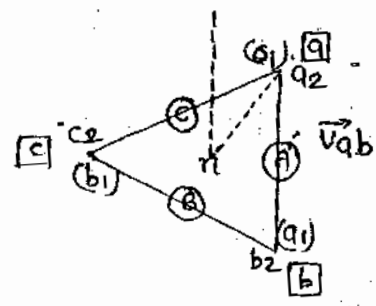
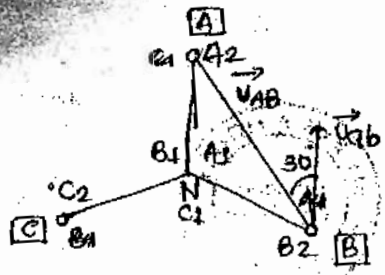
Dd6 →



Yd1 →



Sagar Sen
887145336



Phase vol. Xrmination Ratio = $\frac{V_1 \cdot V_2}{\sqrt{3} \sqrt{3} q_t} = q_t : 1$

line vol. Xrmination Ratio = $v_1 : \frac{V_2}{\sqrt{3} q_t} = \sqrt{3} q_t : 1$

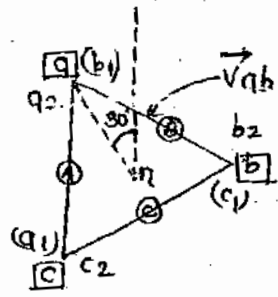
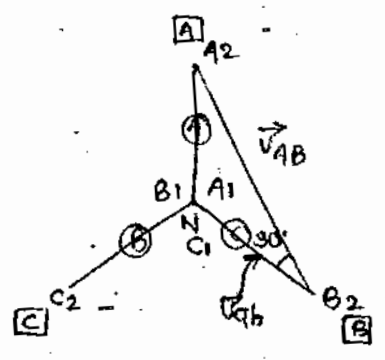
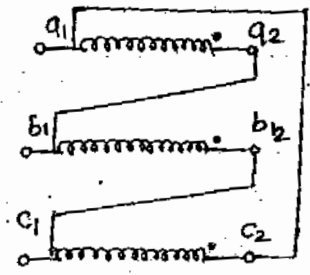
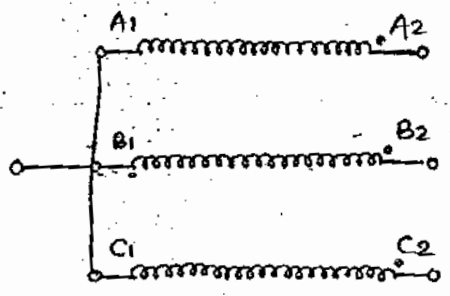
$S_{HV} = \sqrt{3} V_1 I_1$

$S_{LV} = \sqrt{3} \left(\frac{V_2}{\sqrt{3} q_t} \right) (\sqrt{3} q_t I_1)$

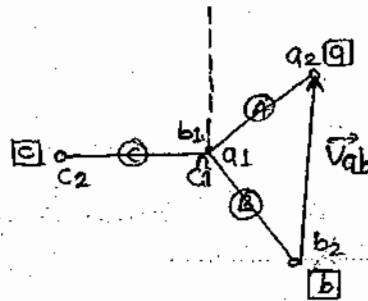
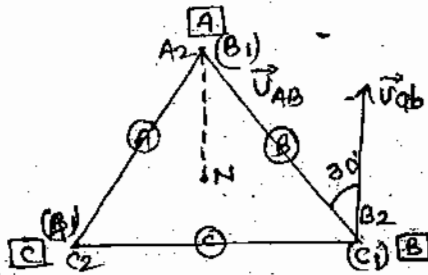
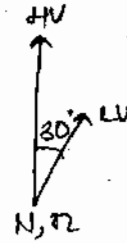
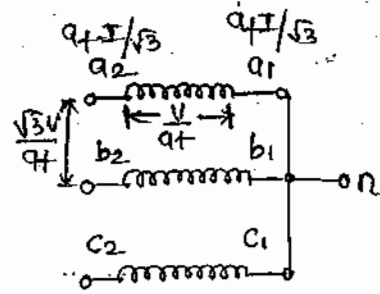
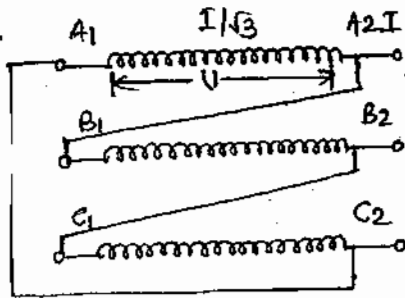
$= \sqrt{3} V_1 I_1$

$S_{LV} = S_{HV}$

Yd11 →



Dy1 →



Hint → Δ limb is decided by λ

Phase vol. X transformation ratio = $V : \frac{V}{q+} = q+ : 1$

line vol. X transformation ratio = $V : \frac{\sqrt{3}V}{q+} = \frac{q+}{\sqrt{3}} : 1$

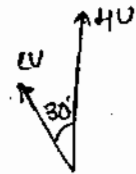
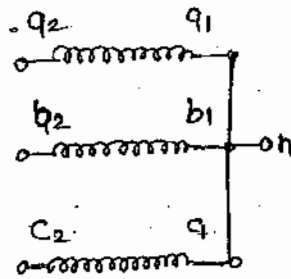
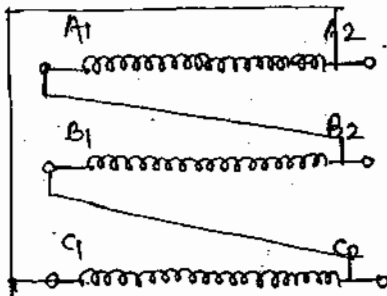
$SHV = \sqrt{3}VI$

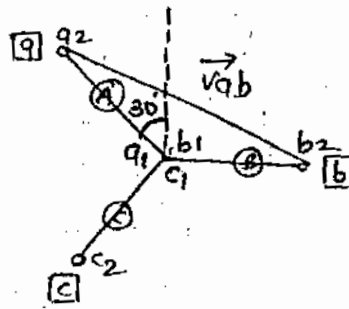
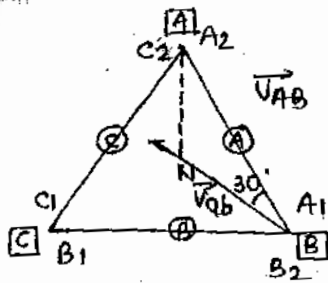
$SLV = \sqrt{3} \left(\frac{\sqrt{3}V}{q+} \right) \left(\frac{q+I}{\sqrt{3}} \right)$

$= \sqrt{3}VI$

$SLV = SHV$

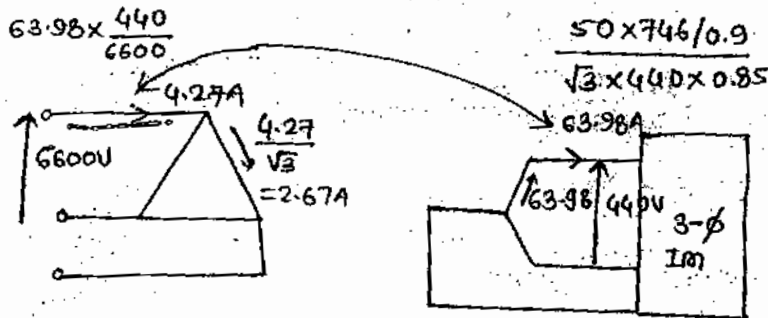
Dy11 →





Que. → A 50HP 440V 3φ-Indⁿ motor with an η of 0.9 at a PF of 0.85 on FL is supplied from a 6600/440V Δ -Y connected Xmer. Ignoring the magnetising current cal. the currents in the HV & LV windings of TF when the motor is running at FL.

Solⁿ →



Que. → A λ - λ - Δ Xmer with 1^o, 2^o & 3^o voltages of 11kV, 1kV & 0.4kV has a magnetising current of 9A. There is a balance load of 600kVA at 0.8 PF lagging on the 2^o wdg & a balance load of 150kW on the 3^o wdg. Neglecting losses, find the 1^o & 3^o phase current if the 1^o PF is 0.82 lag.

Solⁿ →

$$I_1 N_1 = I_2 N_2 - I_3 N_3 - I_0 N_1$$

$$I_1 = \frac{I_2 N_2}{N_1} - \frac{I_3 N_3}{N_1} - I_0$$

$$S_1 = \sqrt{3} \times 11 \times I_1 \cos \phi_1 \text{ kVA}$$

$$S_2 = 600 \cos \phi_2 \text{ kVA} = 600 / 0.8 = 750 \text{ kVA}$$

$$S_3 = \frac{150}{\cos \phi_3} \text{ kVA} \text{ (assuming lag. PF 3^o load)}$$

$$S_0 = \sqrt{3} \times 11 \times 9 \text{ kVA}$$

$$= 170.1 \text{ kVA}$$

$$S_3 = \frac{150}{\cos\phi_3} \angle\phi_3$$

$$= \frac{150(\cos\phi_3 + j\sin\phi_3)}{\cos\phi_3}$$

$$S_3 = 150(1 + j\tan\phi_3)$$

$$S_1 = S_2 + S_2 + S_0$$

$$\sqrt{3} \times 11 \times I_1 \angle\cos^{-1}(0.89) = 600 \angle\cos^{-1}(0.8) + (150 + j150\tan\phi_3) + \sqrt{3} \times 11 \times 3 \angle 90^\circ$$

$$15.623I_1 + j10.905I_1 = 630 + j[360 + 150\tan\phi_3 + 33\sqrt{3}]$$

equating real parts;

$$I_1 = \frac{630}{15.623} = 40.325A$$

equating imaginary parts;

$$10.905 = 360 + 150\tan\phi_3 + 33\sqrt{3}$$

$$\phi_3 = 8.96^\circ$$

$$150 \times 10^3 = \sqrt{3} \times (0.4 \times 10^3) \times I_3(\text{line}) \times \cos(8.96^\circ)$$

$$I_3(\text{line}) = 218.945A$$

$$I_3(\text{ph.}) = \frac{218.945}{\sqrt{3}} = 126.41A$$

$$\boxed{I_1 = 40.32A, I_3 = 126.41A}$$

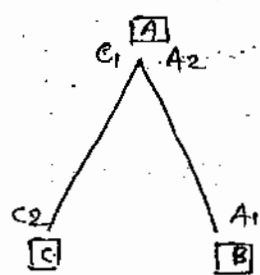
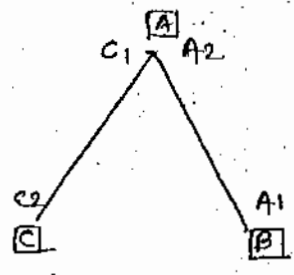
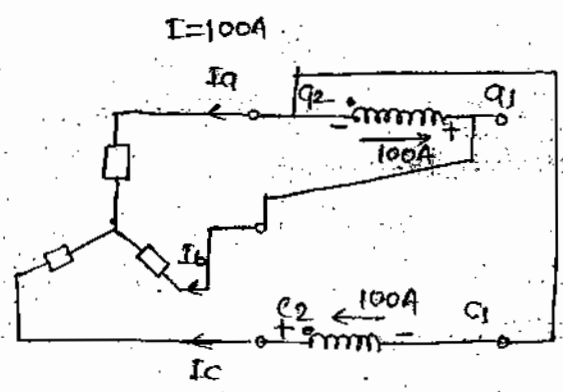
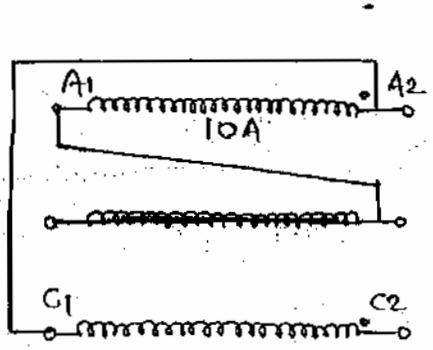
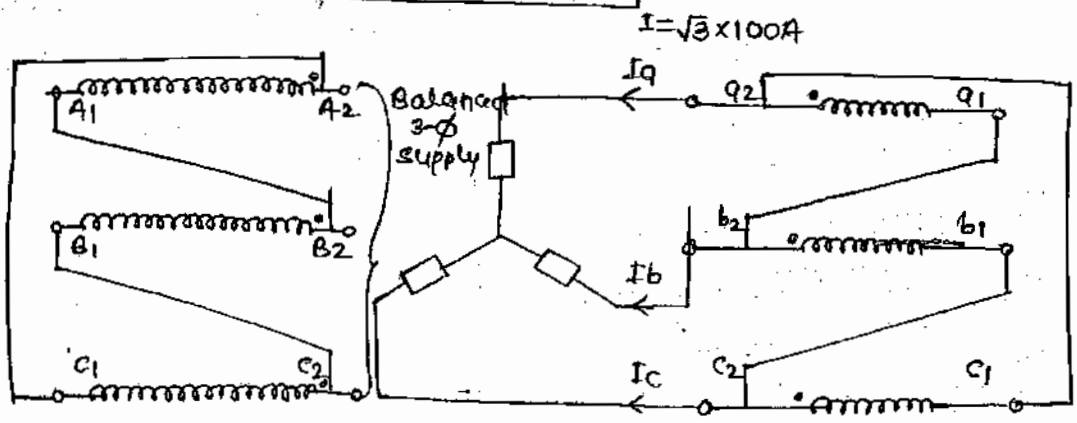
* star is used for HV, low capacity.

* Δ is used for LV, high capacity.

Applications of diff. 3- ϕ TF connections \rightarrow

- * According to the general recommendation a λ connection is used for high vol., low capacity (kVA) appliⁿ where as a Δ connection is favoured for low vol., high capacity appliⁿ.
- * Since the kVA capacity of a TF is same on both sides, the natural choice would be a λ connection for HV side Δ connection for LV side.
- * Accordingly a λ - Δ connection is used for a step down appliⁿ where as a Δ - λ connection is used for step up appliⁿ.
- * However there is an exception. In 2^o distribution sys. a neutral connection is req. to feed 1- ϕ loads as there are mixed ^(3 ϕ & 1 ϕ) loads connected to the system.
Therefore a Δ - λ connection is used in the step down mode in 2^o distribution TF.
- * A Δ - Δ connection is quite suitable to feed 3- ϕ loads of high capacity at LV levels.
If a 3- ϕ bank of 1- ϕ TF is used in Δ - Δ & if one TF has to be removed then the remaining 2 TF may still be used in open Δ (or V) connection to continue to supply 3- ϕ loads although at a reduced capacity of 57.7%.
- * Although a λ - λ connection appears to be quite attractive for HV appliⁿ it is seldom used without a 2^o Δ wdg because of prob. related to magnetising current harmonics, unbalanced loads & unbalanced faults.

Vec(or) Open Δ-connection



$$S_{\Delta-\Delta} = \sqrt{3} V I$$

$$S_{Vee} = \sqrt{3} \cdot V \left(\frac{I}{\sqrt{3}} \right) = VI$$

$$\frac{S_{Vee}}{S_{\Delta\Delta}} = \frac{VI}{\sqrt{3}VI}$$

$$= \frac{1}{\sqrt{3}} = 0.577$$

$$\frac{S_{Vee}}{S_{\Delta\Delta}} = 57.7\%$$

$$S_L = \sqrt{3} V I \phi$$

$$\vec{S}_C = VI \angle \phi + 30^\circ = \frac{S_L}{\sqrt{3}} \angle \phi + 30^\circ$$

$$\vec{S}_A = VI \angle -(30^\circ - \phi)$$

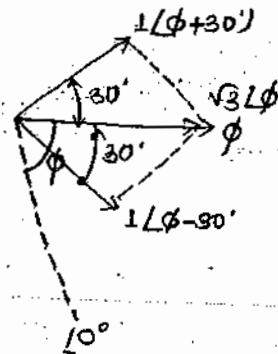
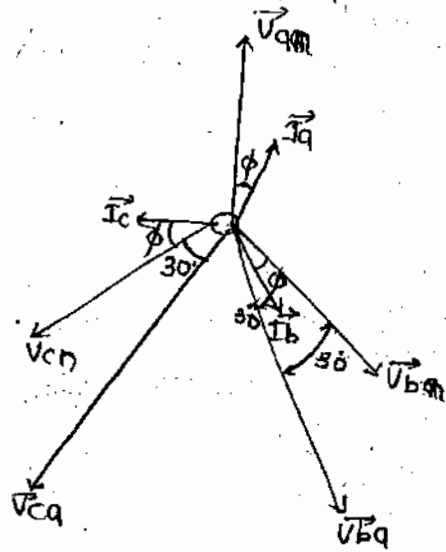
$$\vec{S}_A = VI \angle \phi - 30^\circ = \frac{S_L}{\sqrt{3}} \angle \phi - 30^\circ$$

$$\vec{S}_C + \vec{S}_A = VI [1 \angle \phi + 30^\circ + 1 \angle \phi - 30^\circ]$$

$$= VI [\sqrt{3} \angle \phi]$$

$$= \sqrt{3} VI \angle \phi$$

$$\boxed{S_C + S_A = \vec{S}_{load}}$$



Que. → A 3φ 1000 kVA 0.866 lag PF load is supplied by V connection at 400V. Determine the kVA o/p & operating PF of each TF. Neglect exciting current & all losses.

Sol. →

$$\phi = \cos^{-1}(0.866)$$

$$= 30^\circ \text{ lag}$$

$$\vec{S}_C = \frac{1000}{\sqrt{3}} \angle 30^\circ + 30^\circ$$

$$= 0.577 \angle 60^\circ \text{ kVA}$$

at PF 0.5 lag.

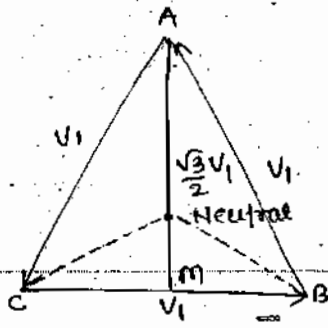
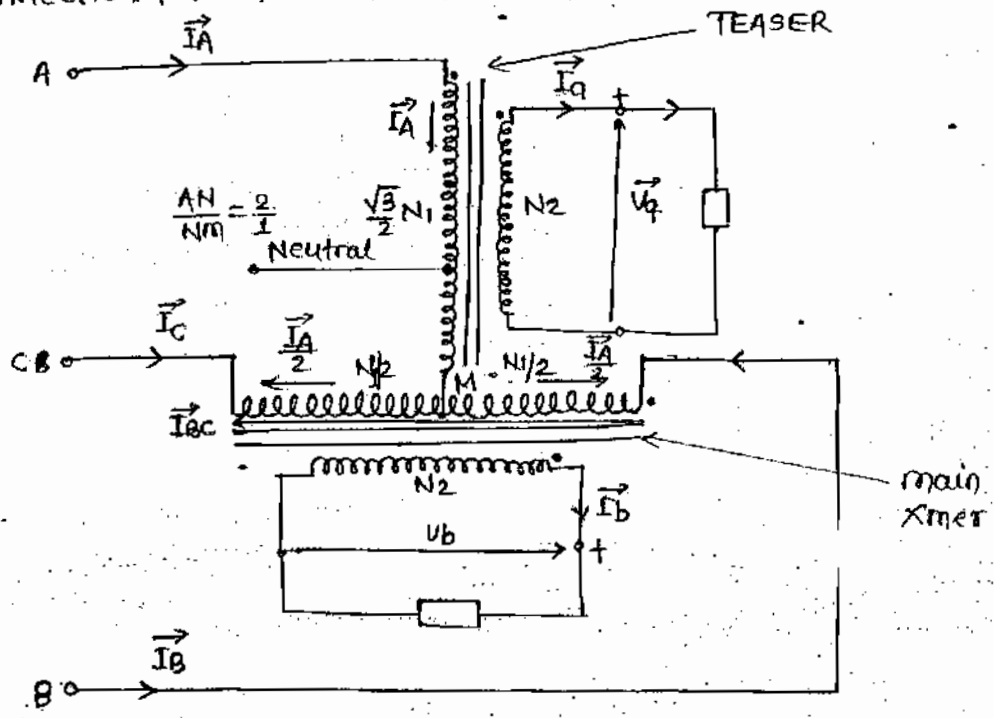
$$\vec{S}_A = \frac{1000}{\sqrt{3}} \angle 30^\circ - 30^\circ$$

$$= 0.577 \angle 0^\circ$$

at PF = 0.

SCOTT CONNECTION

* Scott connection for 3-φ to 2-φ conversion.



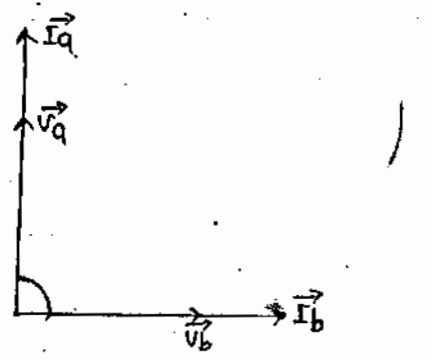
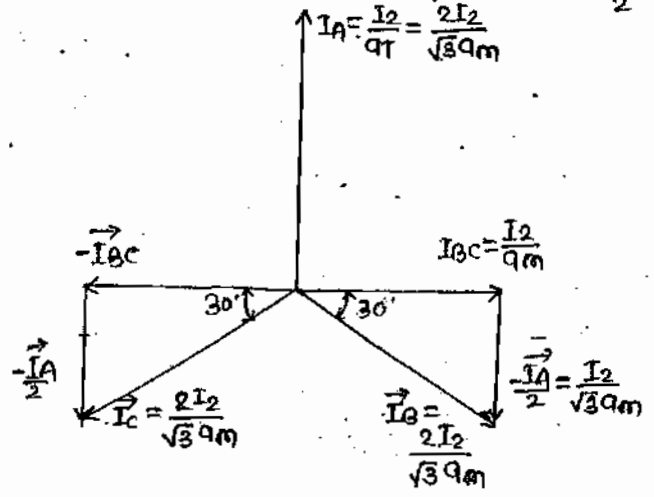
$$q_m = \frac{N_1}{N_2}$$

$$q_T = \frac{\sqrt{3}N_1/2}{N_2} = \frac{\sqrt{3}q_m}{2}$$

$$V_b = \frac{V_1}{q_m} ; V_a = \frac{\sqrt{3}V_1/2}{q_T} = \frac{\sqrt{3}V_1/2}{\sqrt{3}q_m/2}$$

$$V_a = \frac{V_1}{q_m} = V_b$$

$$\vec{I}_B = \vec{I}_{bc} - \frac{\vec{I}_A}{2} ; I_c = -I_{bc} - \frac{I_A}{2}$$



unity pf load. ($I_a = I_b = I_2$)

$$S_{\text{main}} = V_l I_l \quad S_{\text{feeder}} = \frac{\sqrt{3}}{2} V_l \times I_l$$

$$\frac{S_{\text{main}}}{S_{\text{feeder}}} = \frac{2}{\sqrt{3}} = 1.15$$

$$\boxed{\frac{S_m}{S_T} = 1.15}$$

Que. → 2- ϕ furnaces A & B are supplied at 80V by means of Scott connected transformer combination for a 3- ϕ 6600V system. The vol. of furnace A is leading. Cal. the line currents on the 3- ϕ side when

(a) The furnaces take 800kW each at 0.8 PF lag.

(b) Furnace A takes 500kW at UPF & B takes 800kW at 0.707 PF lag.

Soln. → Let; $V_B = 80 \angle 0^\circ$, $V_A = 80 \angle 90^\circ$

$$(a) \quad a_m = \frac{N_1}{N_2} = \frac{6600}{80}$$

$$a_m = 82.5 \quad a_T = \frac{\sqrt{3}}{2} a_m = \frac{\sqrt{3}}{2} \times 82.5 = 71.45$$

$$a_m = 82.5, \quad a_T = 71.45$$

$$I_b = \frac{800 \times 10^3}{80 \times 0.8} \angle -\cos^{-1}(0.8) = 12500 \angle -36.87^\circ A$$

$$I_a = \frac{800 \times 10^3}{80 \times 0.8} \angle 90 - \cos^{-1}(0.8)$$

$$I_a = 12500 \angle 53.13^\circ A$$

$$\vec{I}_{BC} = \frac{\vec{I}_b}{a_m} = 151 \angle -36.87^\circ A, \quad \vec{I}_A = \frac{I_a}{a_T} = 174.95 \angle 53.13^\circ A$$

$$\vec{I}_B = \vec{I}_{BC} - \frac{\vec{I}_A}{2}$$

$$= 174.96 \angle -66.87^\circ A$$

$$I_C = -I_{BC} - \frac{I_A}{2}$$

$$= 174.96 \angle 173.13^\circ A$$

$$\boxed{I_A = 174.95 \angle 53.13^\circ A, \quad I_B = 174.96 \angle -66.87^\circ A}$$

$$\text{---} I_C = 174.96 \angle 173.13^\circ A$$

(b)

$$\vec{I}_b = \frac{800 \times 10^3}{80 \times 0.707} \angle -\cos^{-1}(0.707)$$

$$= 14144.27 \angle -45^\circ \text{ A}$$

$$\vec{I}_q = \frac{500 \times 10^3}{80 \times 1.0} \angle 90^\circ$$

$$= 6250 \angle 90^\circ \text{ A}$$

$$\vec{I}_{bc} = \frac{\vec{I}_b}{9m} = 171.45 \angle -45^\circ \text{ A}$$

$$\vec{I}_A = \frac{\vec{I}_q}{9T} = 87.47 \angle 90^\circ \text{ A}$$

$$\vec{I}_B = \vec{I}_{bc} - \frac{\vec{I}_A}{2} = 204.72 \angle -53.69^\circ \text{ A}$$

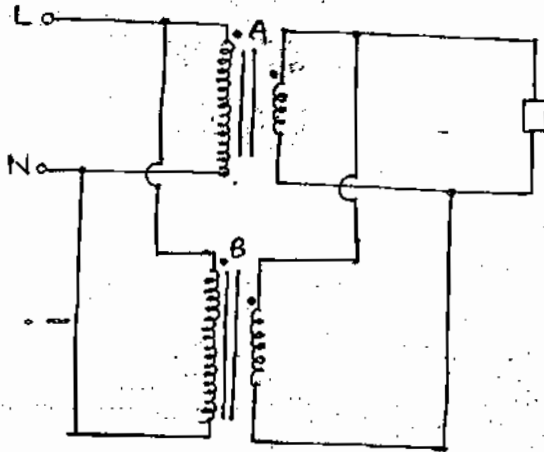
$$\vec{I}_C = -\vec{I}_{bc} - \frac{\vec{I}_A}{2} = 143.89 \angle 147.47^\circ \text{ A}$$

Paralleled Operation OF Transformer

Condⁿ to be satisfied for parallel operation of Xmer →

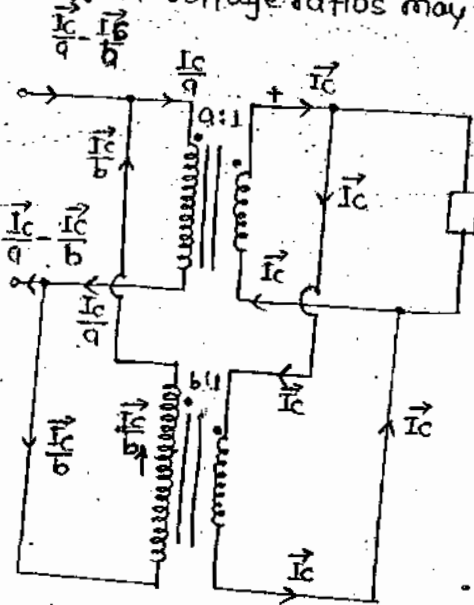
(A) For 1-φ TF & 3-φ TF →

(a) Same polarity. i.e. the dots must be connected to dots. (MUST)



(b) Equal vol. Ratios (same vol. Rating) (MUST)

Note → A small diff. in voltage ratios may be permitted if unavoidable.



$$E_A > E_B$$

$$\frac{V_1}{a} > \frac{V_1}{b}$$

$$b > a$$

$$I_{cB} > I_{cA}$$

$$\frac{I_c}{a} > \frac{I_c}{b}$$

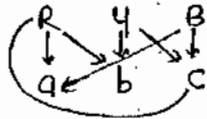
(c) Same pu impedance for proportional load sharing. (desirable)

↓
Name plate Z_{pu}

(d) Same $\frac{X}{R}$ ratios. (i.e. same impedance angle) For same PF operation, as that of the load PF (desirable).

(B) For 3- ϕ TF only \rightarrow

(e) same phase sequence (MUST)



(F) Zero phase diff between the corresponding line voltage.

This means that TF belonging to same phasor group may alone be parallel. (MUST)

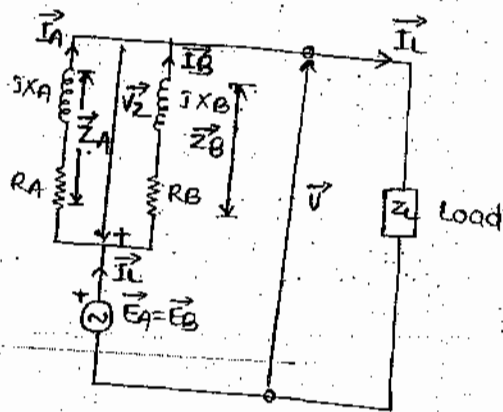
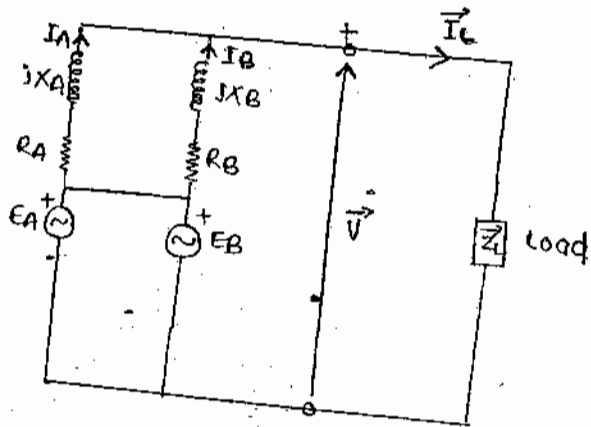
DY11 (a) Y_{y0} (b) Dd0 (c) Y_{y6} (d) Y_{y1}

Because if we change the seq. of 1 $^{\circ}$ then get 30 $^{\circ}$ lead/lag.

LOAD SHARING

Equal Voltage Ratios

$$E_A = E_B$$



Two Xmer;

$$\begin{aligned} \vec{V}_Z &= \vec{I}_A \vec{Z}_A = \vec{I}_B \vec{Z}_B = \vec{I}_L \vec{Z}_P \\ &= \vec{I}_L \times \frac{\vec{Z}_A \vec{Z}_B}{\vec{Z}_A + \vec{Z}_B} \end{aligned}$$

where; Z_A & Z_B are in actual volts.

$$\vec{I}_A = \frac{Z_B}{Z_A + Z_B} \times \vec{I}_L \quad \& \quad \vec{I}_B = \frac{Z_A}{Z_A + Z_B} \times \vec{I}_L$$

However if the impedance are expressed in pu then there pu values should be converted on a common base to insure that the ohmic ratio remain unchanged.

for 'n' Xmers →

$$\vec{V}_Z = \vec{I}_A \vec{Z}_A + \vec{I}_B \vec{Z}_B = \vec{I}_C \vec{Z}_C \dots = \vec{I}_n \vec{Z}_n = \vec{I}_L \vec{Z}_p$$

$$\Rightarrow \vec{I}_A \vec{Z}_A = \vec{I}_L \vec{Z}_p$$

$$\Rightarrow \vec{I}_L = \vec{I}_A \frac{\vec{Z}_A}{\vec{Z}_p}$$

$$\Rightarrow \vec{I}_A \frac{\vec{Z}_A}{\left(\frac{1}{\vec{Z}_A} + \frac{1}{\vec{Z}_B} + \frac{1}{\vec{Z}_C} + \dots + \frac{1}{\vec{Z}_n}\right)} = \vec{I}_L$$

$$\vec{I}_A \vec{Z}_A = \frac{\vec{I}_L}{\left(\frac{1}{\vec{Z}_A} + \frac{1}{\vec{Z}_B} + \dots + \frac{1}{\vec{Z}_n}\right)}$$

$$\vec{I}_A = \frac{\vec{I}_L}{\vec{Z}_A \left(\frac{1}{\vec{Z}_A} + \frac{1}{\vec{Z}_B} + \dots + \frac{1}{\vec{Z}_n}\right)}$$

$$\vec{I}_A = \frac{\vec{I}_L}{\left(\frac{\vec{Z}_A}{\vec{Z}_A} + \frac{\vec{Z}_A}{\vec{Z}_B} + \dots + \frac{\vec{Z}_A}{\vec{Z}_n}\right)}$$

$$S_A = P_A + jQ_A = V_A \vec{I}_A^*$$

$$S_A^* = P_A - jQ_A = V^* \vec{I}_A$$

$$= V^* \frac{\vec{Z}_B}{\vec{Z}_A + \vec{Z}_B} \times \vec{I}_L$$

$$S_A^* = \frac{\vec{Z}_B}{\vec{Z}_A + \vec{Z}_B} \times S_L^*$$

Similarly;

$$\vec{S}_B = \vec{V} \cdot \vec{I}_B^*$$

$$S_B^* = V^* \vec{I}_B$$

$$S_B^* = \frac{\vec{Z}_A}{\vec{Z}_A + \vec{Z}_B} \times S_L^*$$

Per unit loading

$$I_j z_j(\omega) = \text{Constant}$$

$$I_j \propto \frac{1}{z_j(\omega)}$$

$$V \cdot I_j \propto \frac{1}{z_j(\omega)}$$

$$S_j^* \propto \frac{1}{z_j(\omega)}$$

$$S_j^* \propto \frac{1}{z_j(\text{pu}) \times z_j(\text{Base})}$$

$$S_j^* \propto \frac{1}{z_j(\text{pu}) \times \left[\frac{V_{\text{rated}}^2}{S_{j(\text{rated})}} \right]}$$

$$S_j^* \propto \frac{S_{j(\text{rated})}}{z_j(\text{pu})}$$

$$\frac{S_j^*}{S_{j(\text{rated})}} \propto \frac{1}{z_j(\text{pu})}$$

$$S_j^*(\text{pu}) \propto \frac{1}{z_j(\text{pu})}$$

* This means that the TF with lowest pu impedance on its own base (i.e. name plate z_{pu}) would have max^m pu loading & therefore would be the 1st ^{to} reach its FL.

for proportional load sharing

$$S_j \propto S_{j(\text{rated})}$$

$$\frac{S_j}{S_{j(\text{rated})}} = \text{constant}$$

$$S_j(\text{pu}) = \text{constant}$$

$$\text{Since } S_j(\text{pu}) \propto \frac{1}{z_j(\text{pu})}$$

\therefore for proportional load sharing

$$z_j(\text{pu}) = \text{constant}$$

Que. → 2- ϕ Xmers rated 1000 kVA & 500 kVA respectively are connected in parallel on both HV & LV sides. They have equal voltage ratings of 11 kV/400V & their pu impedances are $0.02 + j0.07$ & $0.0455 + j0.0788$ pu respectively.

(A) How will the following loads will share
 360 kVA at 0.9 PF lagging.
 500 kW at UPF.

(B) What is the largest value of 0.8 PF lagging load that can be delivered by the parallel combination at the rated vol.
 Determine the load shared & operating pf of the 2 TF under these condⁿ.

Solⁿ → $Z_A = 0.0728 / 74.05^\circ \text{ pu}$; $Z_B = 0.091 / 60^\circ \text{ pu}$

Because the value of the Z_A is less, then it will go for FLTST

Selecting 1000 kVA as common base ; Z_A will same

$$(Z_B)_{\text{new}} = 0.091 / 60^\circ \times \frac{1000}{500}$$

$$(Z_B)_{\text{new}} = 0.182 / 60^\circ \text{ pu}$$

$$S_L = 360 \text{ kVA}$$

Part (A)

$$(i) S_L = 360 / 25.84^\circ \text{ pu kVA}$$

$$\vec{S}_A^* = \frac{(Z_B)_{\text{new}}}{Z_A + (Z_B)_{\text{new}}} S_L^*$$

$$= \frac{0.182 / 60^\circ}{0.0728 / 74.05^\circ + 0.182 / 60^\circ} \times 360 / 25.84^\circ$$

$$= 258.78 / -29.84^\circ \text{ kVA}$$

i.e. 224.42 kW at 0.8674 PF lagging.

For 2 TF only, $S_B = \vec{S}_L - \vec{S}_A$

& for 1 TF $S_B^* = \frac{Z_A}{Z_A + Z_B(\text{new})} \times S_L^*$

$$\vec{S}_B = 103.49 \angle 15.8^\circ \text{ kVA}$$

i.e. 99.58 kW at 0.9622 PF lag.

$$\text{Qii) } S_L = \frac{500}{10} \angle 0^\circ \text{ kVA}$$

$$S_A^* = \frac{Z_B(\text{new})}{Z_A + Z_B(\text{new})} \times 500 \angle 0^\circ$$

$$= 359.34 \angle -4^\circ \text{ kVA}$$

i.e. 358.47 kW at 0.9976 PF lag.

For 2 Xmer only; $\vec{S}_B = \vec{S}_L - \vec{S}_A$

$$\text{If TF use common formula } S_B^* = \frac{\vec{Z}_A}{\vec{Z}_A + \vec{Z}_B(\text{new})} \times S_L^*$$

$$\vec{S}_B = 143.74 \angle -10.04^\circ \text{ kVA}$$

i.e. 141.54 kW at 0.9647 PF lead.

(B) Since $S_{pu} \propto \frac{1}{Z_{pu}}$; TF A would reach FL; 1st

$$S_{pu} \propto \frac{1}{Z_{pu}}$$

$$Z_A < Z_B$$

Then $\vec{S}_A = 1000 \angle 0^\circ \text{ kVA}$

$$\text{Since } S_j^* \propto \frac{1}{Z_j(\Omega)}$$

$$\frac{S_B^*}{S_A^*} = \frac{Z_A(\Omega)}{Z_B(\Omega)} \quad \text{OR} \quad \frac{S_B^*}{S_A^*} = \frac{\vec{Z}_A}{\vec{Z}_B(\text{new})}$$

$$S_B^* = S_A^* \frac{Z_A}{Z_B(\text{new})}$$

$$S_L^* = S_A^* + S_B^*$$

$$= S_A^* + S_A^* \times \frac{\vec{Z}_A}{\vec{Z}_B(\text{new})}$$

$$= S_A^* \left[1 + \frac{\vec{Z}_A}{\vec{Z}_B(\text{new})} \right]$$

$$S_L^* = S_A^* [1.3914 \angle 4^\circ]$$

$$= 1000 \angle -\phi_A * 1.3914 \angle 4^\circ$$

$$S_L \angle -36.87^\circ = 1391.4 \angle 4^\circ - \phi_A \text{ kVA}$$

$$\text{Max } S_L = 1391.4 \text{ kVA}$$

$$\text{Equating angles } \Rightarrow -36.87^\circ = 4^\circ - \phi_A$$

$$\phi_A = 40.87^\circ$$

$$\text{i.e. } \vec{S}_A = 1000 \angle 40.87^\circ \text{ kVA}$$

$$742.756.2 \text{ kW at } 0.7562 \text{ PF lag.}$$

$$\text{New } \vec{S}_B = S_L - S_A \text{ for 2 TF}$$

$$\text{Also in general } S_B^* = S_A^* \frac{\vec{Z}_A}{\vec{Z}_B(\text{new})}$$

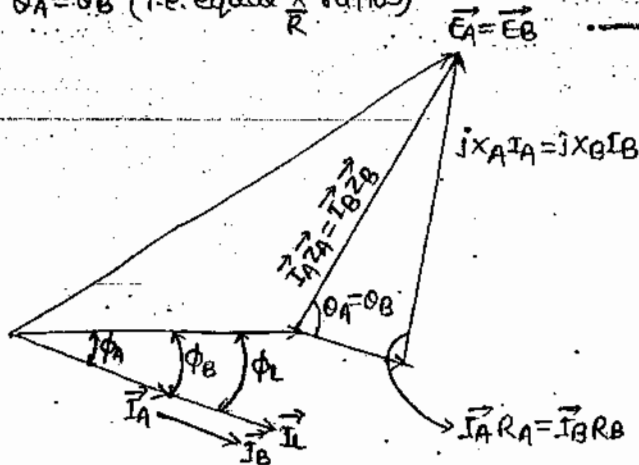
$$\vec{S}_B = 399.97 \angle 26.83^\circ \text{ kVA}$$

$$\text{i.e. } 356.92 \text{ kW at } 0.8923 \text{ PF lag.}$$

Phasor diagram →

$$E_A = E_B$$

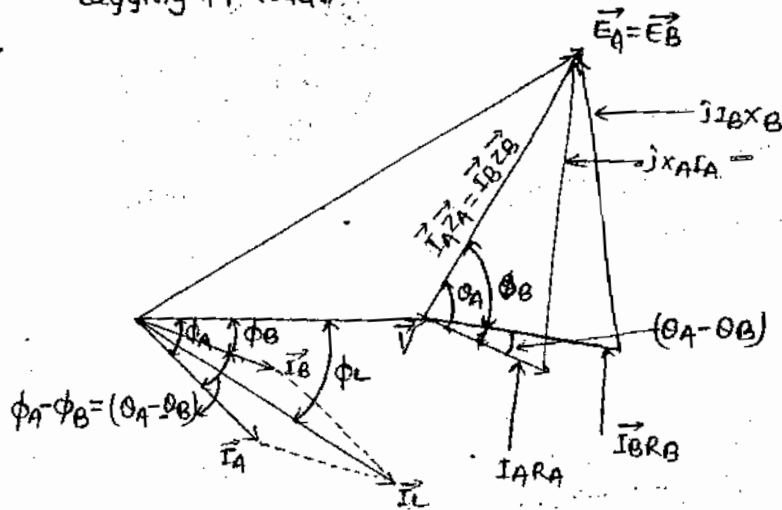
$$\theta_A = \theta_B \text{ (i.e. equal } \frac{X}{R} \text{ ratios)}$$



$$E_A = E_B$$

$\theta_A > \theta_B$ (a unequal $\frac{X}{R}$ ratio)

lagging PF load.



Unequal Voltage Ratios →

$$E_A > E_B$$

$$E_A = \vec{V} + \vec{I}_A \vec{Z}_A$$

$$= (\vec{I}_L \vec{Z}_L) + \vec{I}_A \vec{Z}_A$$

$$\vec{E}_A = (\vec{I}_A + \vec{I}_B) \vec{Z}_L + \vec{I}_A \vec{Z}_A$$

$$(\vec{Z}_A + \vec{Z}_B) \cdot \vec{I}_A + \vec{I}_B \vec{Z}_L = \vec{E}_A \quad \text{--- (i)}$$

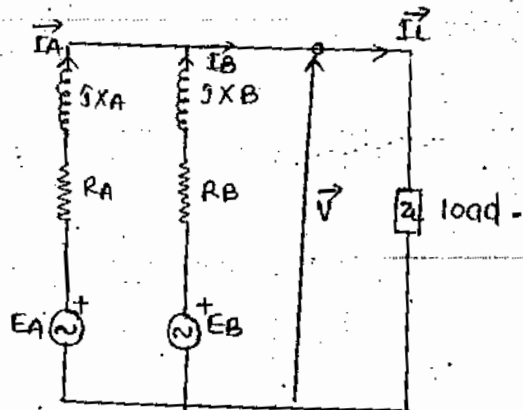
steps → $\vec{Z}_L \vec{I}_A + (\vec{Z}_B + \vec{Z}_L) \vec{I}_B = \vec{E}_B \quad \text{--- (ii)}$

(i) calculate \vec{I}_A & \vec{I}_B

(ii) $\vec{I}_L = \vec{I}_A + \vec{I}_B$

(iii) $\vec{V} = \vec{I}_L \vec{Z}_L$

(iv) $\vec{S}_A = \vec{V} \cdot \vec{I}_A^*$; $\vec{S}_B = \vec{V} \cdot \vec{I}_B^*$



Use of Millman's theorem (OR) parallel generator theorem →

steps →

(i) $\vec{V} = \vec{I}_{sc} \vec{Z}_p$

where $\vec{I}_{sc} = \sum_{j=1}^n \frac{E_j}{Z_j}$

$$\frac{1}{Z_p} = \frac{1}{Z_L} + \sum_{h=1}^n \frac{1}{Z_h}$$

$$(2) \vec{I}_j = \frac{\vec{E}_j - \vec{V}}{Z_j} \quad \text{where; } j=1, 2, \dots, n.$$

$$(3) \vec{S}_j = \vec{V} \cdot \vec{I}_j^* \quad \text{where; } j=1, 2, \dots, n$$

$$\vec{S}_L = \sum_{j=1}^n \vec{S}_j$$

Calculation check

$$\vec{S}_L = \vec{V} \cdot \vec{I}_L^*$$

$$\text{Also; } \vec{S}_L = \frac{(V)^2}{Z_L^*}$$

$$= V \cdot \left(\frac{V}{Z_L}\right)^*$$

$$= \frac{V \cdot V^*}{Z_L^*}$$

$$= \frac{V^2}{Z_L^*}$$

Que. → 2, TF A & B are connected in parallel to a common load $2 + j1.5 \Omega$. Their impedances in Z° terms are $Z_A = (0.15 + j0.5) \Omega$ & $Z_B = (0.1 + j0.6) \Omega$. Their NL terminal voltages are $E_A = 20 \angle 0^\circ$ & $E_B = 20 \angle 0^\circ$. Find the power o/p & PF of each TF.

Solⁿ →

$$\vec{I}_{sc} = \frac{\vec{E}_A}{Z_A} + \frac{\vec{E}_B}{Z_B}$$

$$= \frac{20 \angle 0^\circ}{(0.15 + j0.5)} + \frac{20 \angle 0^\circ}{0.1 + j0.6}$$

$$= 782.105 \angle -76.625^\circ$$

$$\frac{1}{Z_p} = \frac{1}{Z_L} + \frac{1}{Z_A} + \frac{1}{Z_B}$$

$$(Z_p)^{-1} = (Z_L)^{-1} + (Z_A)^{-1} + (Z_B)^{-1}$$

$$Z_p = 0.258 \angle 72.85^\circ$$

$$\vec{V} = \vec{I}_{sc} \cdot Z_p$$

$$= 189.25 \angle -3.78^\circ \text{ V}$$

$$I_A = \frac{E_A - \vec{V}}{Z_A} + \frac{E_B - \vec{V}}{Z_B} = 42.2 \angle -38.81^\circ \text{ A}$$

$$I_B = \frac{E_B - \vec{V}}{Z_B} = 33.57 \angle -42.87^\circ \text{ A}$$

$$S_A = V \cdot I_A$$

$$= 7.988 \angle 35.03^\circ \text{ kVA}$$

$$\text{i.e. } 6.54 \text{ kW at } \cos 35.03^\circ \text{ lag}$$

$$\text{i.e. } 0.8189 \text{ PF lag}$$

$$S_B = V \cdot I_B^*$$

$$= 6.853 \angle 39.09^\circ \text{ kVA}$$

$$\text{i.e. } 4.931 \text{ kW at } \cos 39.09^\circ \text{ PF lag}$$

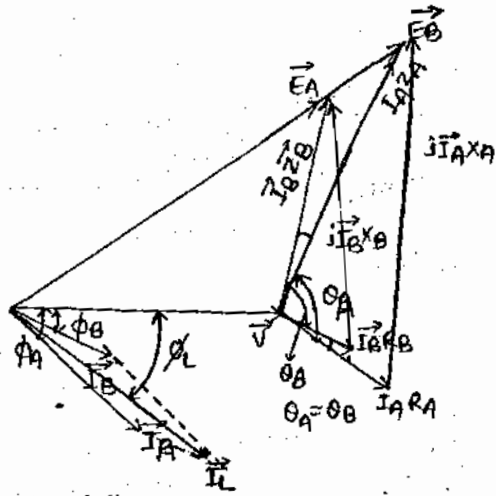
$$\text{i.e. } 0.7762 \text{ PF lag}$$

$$S_L = S_A + S_B$$

$$= 14.332 \angle 36.828^\circ$$

Phasor diagram →

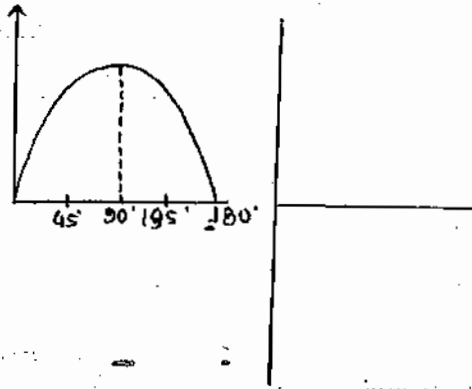
$E_A > E_B$, $\theta_A = \theta_B$, lagging PF load.



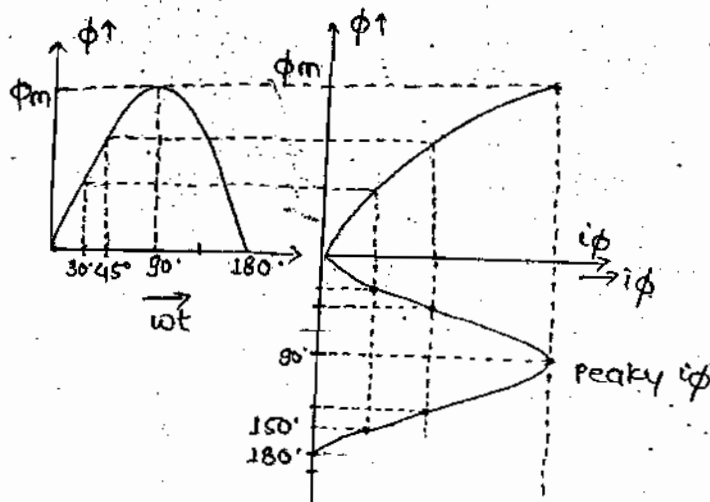
* Magnetisation Current phenomenon in the TF →

* If the applied vol. to the TF is sinusoidal then the core flux should also be sinusoidal.

* If the magnetisation curve of core material would have been linear then the magnetising current would also have been sinusoidal.



* Modern TF are operated with high flux density in the core due to economic reason & this drives the core into deep saturation.
Obviously the magnetisation curve becomes highly non-linear.



* With such a non-linear magnetisation c/s a sinusoidal flux may only be obtained with a peaky magnetising current containing dominant a 3rd harmonic component.

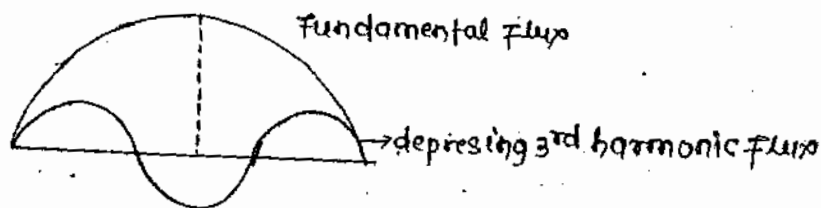
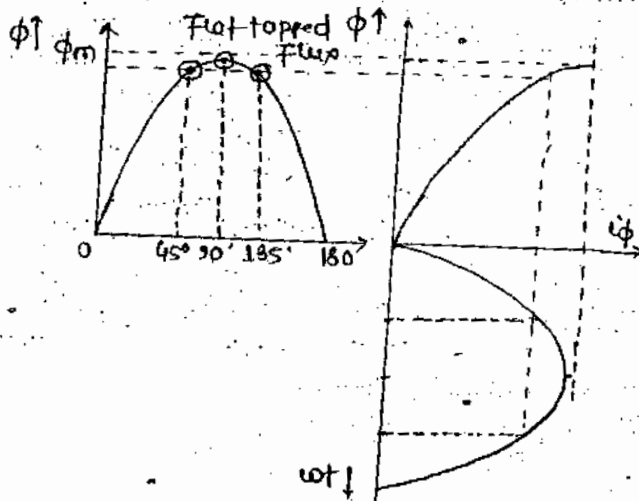
3. The 3rd harmonic component of the magnetising current may flow only if the electric circuit permits.

Thus it can easily flow in 2- ϕ TF or 1- ϕ circuit. However in 3- ϕ TF the 3rd harmonic current of 3 phasors are all in phase; thereby constituting 0 seq. current.

Hence they can flow only in the 1^o star neutral of the TF is connected to the source neutral (or) it can flow in closed Δ .

* In a λ - λ TF there is no path for flow of 3rd harmonic components of magnetising current & therefore the magnetising current remains sinusoidal if higher non-triplank odd harmonics are neglected.

* With a sinusoidal magnetising current the core flux becomes flat topped containing dominant depressing 3rd harmonic flux component.



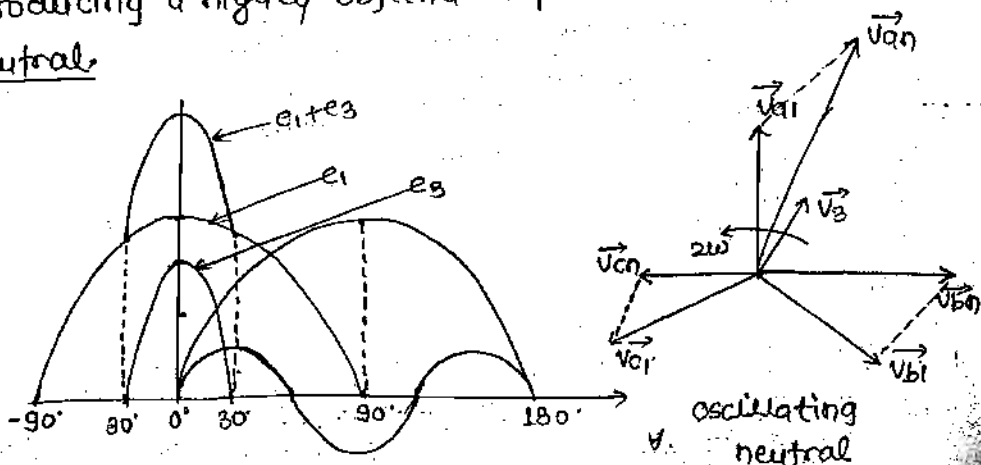
* The 3rd harmonic component of flux may get easily established only if magnetic ckt permits.

Hence the 3rd harmonic flux components may get established easily in those TF that have independent magnetic ccts such as in 3- ϕ bank of 1- ϕ TF, 3 ϕ shell type TF & 5 limbed (or 4 limbed) core type TF.

* Consequently in magnetically independent TF the 3rd harmonic flux gets strongly established resulting into a peaky induced emf in both wdg's; that in creates high insulation stress in both wdg's in addition to producing a highly objectionable phenomenon called Oscillating neutral.

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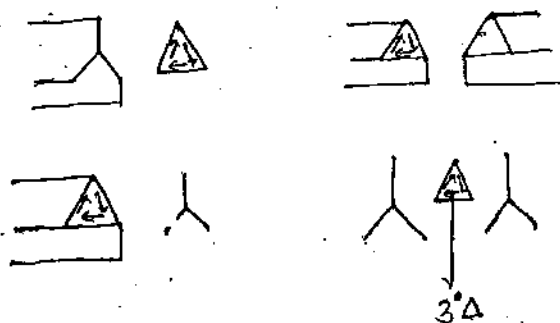
$$\vec{I}_{a3} = \vec{I}_{b3} = \vec{I}_{c3} = \vec{I}_3$$



* The solⁿ to the above prob. is to provide a 3°Δ wdg in a λ-λ TF so that the electric ckt permits flow of 3rd harmonic components in the closed 3°Δ, that eventually would restore harmonic variation to the core flux.

* The presence of a Δ-wdg provides a low reluctance path for 0-seq. currents & therefore restores harmonic variation (sinusoidal) to the core flux & also facilitates 1-φ loads besides reducing the effect of floating (or) shifting neutral.

It also prevents current choking in λ-λ TF. The presence of Δ also helps in detection of unsymmetrical faults; particularly those involving ~~down~~ ground.



The problems discussed above relate to those TF that have magnetically independent ckt's.

However a 3-limb core type TF has magnetically interlinked ckt & therefore the 3rd harmonic flux forming a seq. finds a very high reluctance path through air & tank valves.

Consequently the magnitude of 3rd harmonic flux remains extremely low although it ultimately results in tank valve heating.

Therefore large 3 limb core TF are provided with a cu ring that surrounds the core thereby providing a cu screen for the 3rd harmonic flux & minimized tank valve heating.

Hence a 3-limbed core type TF may be connected in Δ - Δ without a 3 Δ . However if the unbalance is expected to exceed then it is recommended to use a 3 Δ wdg.

* A 3 limbed core type TF does not permit easy access to 3rd harmonic flux & this results into increased 5th & 7th harmonic components in the magnetising current.

These component can't be suppressed by any electric connection. Hence if these harmonics are objectionable then a 4-limbed (or) 5 limbed st. should be provided.

Notes: The 1 ϕ neutral in a Δ - Δ connection is not connected to the gen^r neutral to provide a path for 3rd harmonic component of magnetising current.

This is because the gen^r ϕ vol. itself contain 3rd harmonic vol. & this would appear across the 1 ϕ of TF.

Obviously then the 2 ϕ would now contain 3rd harmonic vol. component in all its 3- ϕ .

Since the 2 ϕ neutral would be grounded, 3rd harmonics currents would flow in the x η line resulting into objectionable communication interference. Thus the other alternative of providing a 3 Δ wdg is adopted to allow flow of 3rd harmonics of magnetising current.